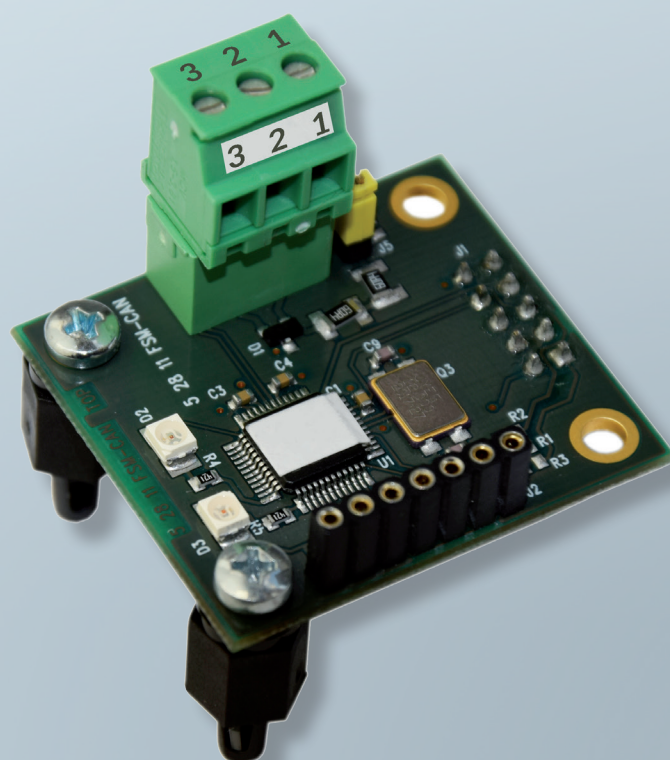


## FSM-CAN MODULE

Installation and Commissioning Manual



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<b>First edition</b>	31/01/2019
<b>Author</b>	AL / EP
<b>Last change</b>	14.12.2020 / AME
<b>Release</b>	14.12.2020 AL
<b>Hardware version</b>	V1.1
<b>Software version</b>	V1.0
<b>Doc. no.</b>	hb_FSM CAN Modul_2020-04_2.3._en
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# 1 General

These instructions describe an optional installation assembly for interference suppression of the safety circuit inputs of the lift control system.

It serves as a supplement to the FST manual and the FST Installation and Commissioning Manual. The manual is limited exclusively to the description of the aspects relevant to the function.



*The safety guidelines of the FST manual and the FST Installation and Commissioning manual always apply.*

## 1.1 Abbreviations, characters and symbols used

Symbol / abbreviation	Meaning
FSM	Car top control module
FSM-CAN	CAN module for FSM
FST	Field bus controller
GST	Group controller
ADM	Landing call module
SAM	Speech output module
FPM	Car operating panel module
Menu	Menu integrated in the TFT for editing display settings
▶	<b>Operational instructions</b> Perform the tasks that follow this symbol in the specified order.
•	<b>Action step under the respective operational instruction</b>
	<b>Safety information</b> This symbol is located in front of safety-relevant information.
	<b>Information notice</b> This symbol is located in front of relevant information.

## 1.2 Notation

Notation	Meaning
<b>Bold</b>	› Designations of switches and actuators › Input values
<i>Italics</i>	› Captions › Cross references › Designations of functions and signals › Product names
<b><i>Bold italics</i></b>	› Remarks
LCD font	› System messages of the controller

## 1.3 Further information

The following documents, among others, are available for the FST controller and its components.

- › ADM manual
- › EAZ TFT.45.110.210 manual
- › EAZ-256 manual
- › EN81-20 manual
- › FPM manual
- › FST-2XT/s manual
- › FST-2XT MRL manual
- › FST installation and commissioning manual
- › GST-XT manual
- › LCS manual
- › RIO manual
- › SAM manual
- › UCM-A3 manual
- › Update backup analysis manual

These and other current manuals can be found in the download area of our website at  
<https://www.newlift.de/downloads-311.html>

## 1.4 How to contact us

If, after referring to this manual, you still require assistance, our service line is there for you:

Phone +49 89 - 898 66 - 110  
E-mail [service@newlift.de](mailto:service@newlift.de)  
Mon. - Thurs.: 8:00 a.m. - 12:00 p.m. and 1:00 p.m. - 5:00 p.m.  
Fr: 8:00 a.m. - 3:00 p.m.

## 2 Safety

All modules of the installation assembly must only be operated in perfect working condition in a proper manner, safely and in compliance with the instructions, the valid accident prevention regulations and the guidelines of the local power company.



*The safety guidelines of the FST manual and the FST Installation and Commissioning manual apply for this product.*

### 2.1 Handling electronic assemblies



#### Electrostatic charging

- ▶ Keep the electronic assembly in its original packaging until installation to prevent damage.
- ▶ Before opening the original packaging, a static discharge must be performed!  
To do this, touch a grounded piece of metal.
- ▶ During work on electronic assemblies, periodically repeat this discharge procedure!
- ▶ Equip all bus inputs/outputs not in use with a terminal resistor (terminator) to prevent malfunctions.

### 3 Commissioning the FSM CAN

#### Connection and settings

- ▶ Update control software  
Update to FST (V2.000-0147) and FSM (V2\_V51) or higher
- ▶ Connect FSM CAN:  
Wiring according to figure "Wiring CAN door control device – FSM" (see page 8).
- ▶ Setting the door control device
  - AT40 menu:
    - › German
      - › Total adjustment
        - › Special parameters
          - » Commands sent via = CAN
          - » CANopen node-ID (see table)
          - » Baudrate = 250 Kbit/s
          - » Door number (see table)

Door	O	B
Node-ID	7	8
Door number	1	2

- Set Mi-drive via Meiller app
- ▶ Set FST controller in FST menu
  - >doors
  - >Doors-Selective
    - >>Type = CAN (for A11 / A / B)
    - >>Endswitches = NO
    - >>Deenergize = YES

#### Flash code table

Red LED	Green LED	
ON	OFF	Switch-on state
Flashing	OFF	FST/FSM-CAN connection OK FSM-CAN waiting for connection with door drive
OFF	Flashing	FST/FSM-CAN connection OK FSM-CAN establishing connection with door drive (pre-operational)
OFF	ON	Operational

Rev.

1.0

Gez.

06.06.18

Freig.

29.11.19

Beschreibung

Neu erstellt  
Nummerierung AT40 geändert

Cable: LIYCY TP 2x2x0,25mm or similar  
(4 core, twisted pair, complete twisted, screened)

Plugtyp (usable for all 3 devices):  
Phoenix MCVW 1,5/3-ST-3,81  
Art. Nr. 1826982

Termination must always be set at the end of the cable line!

X4

Termination: ON

FSM with  
FSM-CAN  
Modul


Termination: OFF

Door A

Termination: ON


Door B

Siemens Sidor AT40



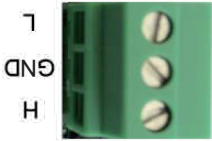
H  
GND  
L

Meiller MiDrive



GND  
H  
L

FSM CAN



H  
GND  
L

Pin configuration:

Plug	1	2	3	
FSM CAN	X4	H	GND	L
Siemens Sidor AT40	X16	H	GND	L
Meiller MiDrive	DS417	L	H	GND

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D-82166 Gräfelfing

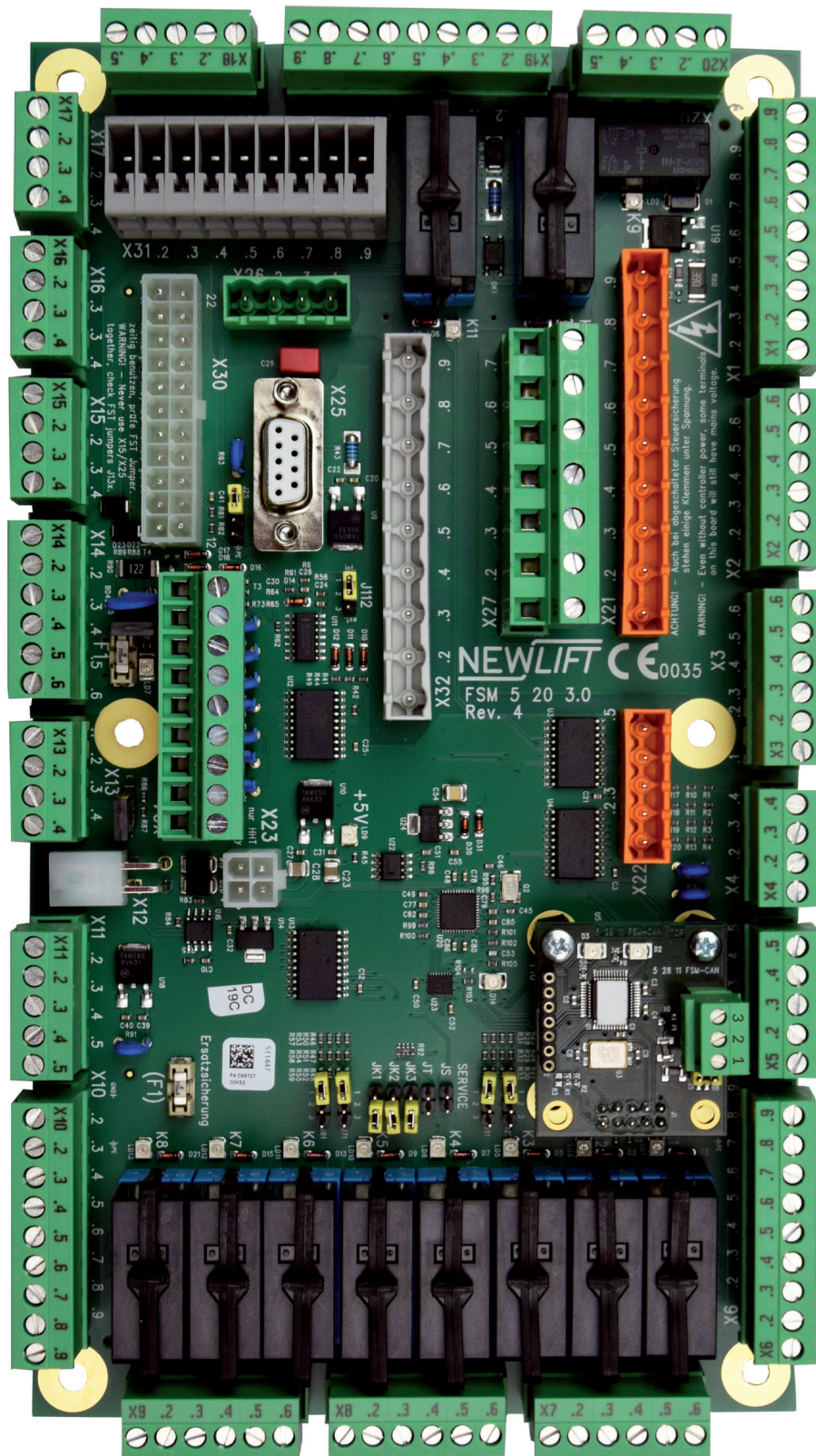
Cabling CAN-Door controller - FSM

Seite 1 von 1

8

Installation & Commissioning Manual FSM CAN





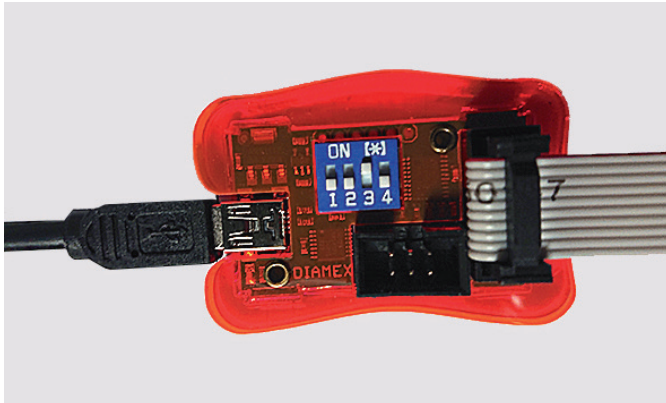
FSM circuit board with CAN module

## 4 Programming adapter

The controller of the FSM-CAN cannot be programmed via the LON bus. A special programming adapter is needed for this purpose. The programming adapter for the software update can be ordered from NEWLift under the following part number:

- › USB ISP programmer for FSM-CAN - Part No. 37-88700

### 4.1 Connecting the programming adapter

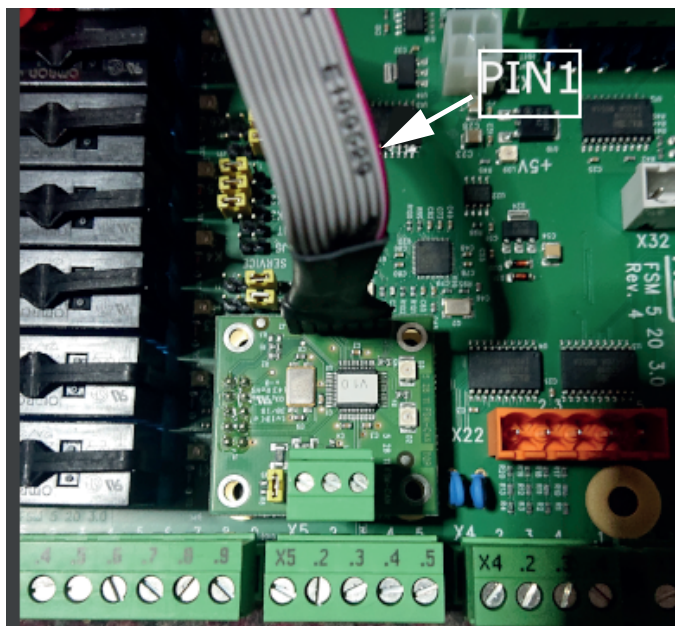


*Programming adapter*

- ▶ Set DIP switch 3 to ON.
- ▶ Use the USB cable to connect the programming adapter to the PC.
- ▶ Connect the programming adapter to the FSM-CAN module with the ribbon cable:
  - Connect 10-pin box header to the programming adapter.
  - Connect 7-pin pin header to J2 of the FSM-CAN module.



**Pay attention to the polarity of the cable!**



*Connection of FSM-CAN module*

- ▶ Supply the FSM-CAN module with 24 V via, e.g., X30.

## 4.2 Installing the software

### Requirement

- › File *FSM-CAN\_flasher.zip*
- › Runs on Windows XP and newer
- › Driver
  - » No driver necessary beginning with Windows 10
  - » For older versions of Windows, please check with NEWLift

The software is included in the delivery contents and is provided on a USB stick.

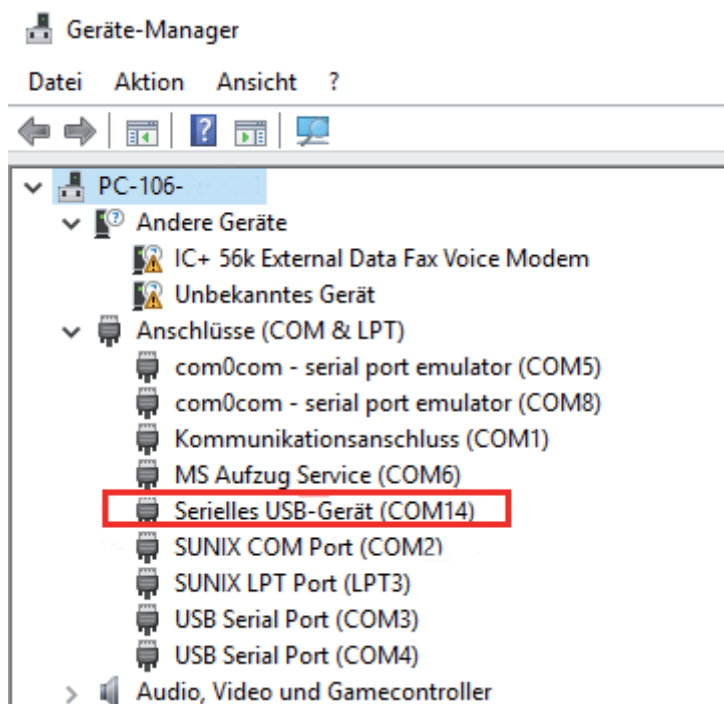
### Installation

- ▶ Use a USB cable to connect the programming adapter to the PC  
„4.1 Programmieradapter anschließen“ auf Seite 10.
- ▶ Extract the ZIP file to a directory of your choice on the PC or USB stick.
- ▶ In the Windows device manager, select the unknown device with the right mouse button.
- ▶ Select the **Update driver software** function and confirm.
- ▶ In the following window, navigate to the directory containing file *prog-s2-isp.inf*
- ▶ Start file *prog-s2-isp.inf*.

With Windows 10, no further driver installation is necessary; the programmer automatically registers as a serial USB device.



*Note the number of the COM port for your device.*



*Example for COM port*



### 4.3 Using the software

The application file is contained in file *FSM-CAN\_flasher.zip*.

► Enter *progfsm.bat X* via the console

or

► in the extracted *FSM-CAN\_flasher* directory, execute the application by double-clicking on one of the *progfsm\_COMX.bat* files.



*X stands for the COM number of your programming device, e.g., progfsm\_COM14.bat.*

#### Normal program execution

```

C:\> F:\flasher>cd flasher

F:\flasher\flasher>fm.exe COM(14,57600) DEVICE(LPC11C24/301, 0.000000, 0) HARDWA
RE(BOOTEXEC, 50, 100) ERASE(DEVICE, PROTECTISP) HEXFILE(hexfiles\fsm_can_1_02.he
x, NOCHECKSUMS, NOFILL, PROTECTISP) VERIFY(hexfiles\fsm_can_1_02.hex, NOCHECKSUM
S)
Flash Magic Version 11.20.5190
8051/XA Driver Version 3.55.5190
ARM UART Driver Version 5.06.5189
ARM Cortex UART Driver Version 8.41.5185
ARM Ethernet Driver Version 2.25.5190
ARM Cortex Ethernet Driver Version 2.70.5189
ARM CAN Driver Version 3.36.5044
(C) Embedded Systems Academy 2000-2018 All rights reserved
NON PRODUCTION USE ONLY
Connected
Device selected
Erase complete (DEVICE)
Hex file programming complete (hexfiles\fsm_can_1_02.hex)
Verify passed (hexfiles\fsm_can_1_02.hex)

F:\flasher\flasher>cd..
F:\flasher>
  
```

Screen display for normal/error-free program execution

#### Faulty program execution

```

C:\> F:\flasher>progfsm_COM14.bat

F:\flasher>REM Argument arg1 = COM Port  ist Argument aus Commandozeile

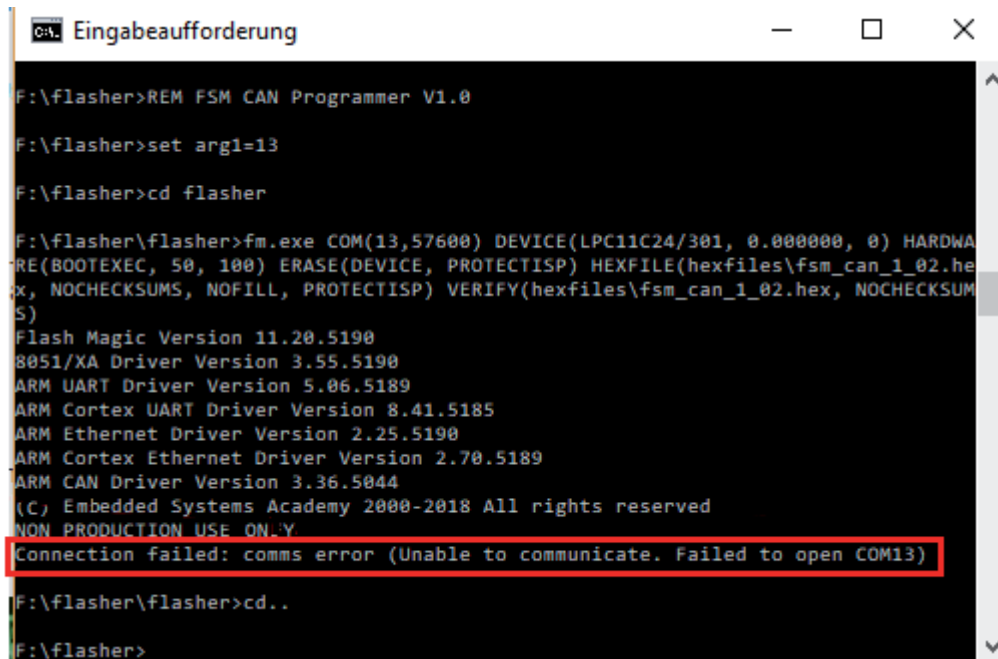
F:\flasher>REM FSM CAN Programmer V1.0

F:\flasher>set arg1=14

F:\flasher>cd flasher

F:\flasher\flasher>fm.exe COM(14,57600) DEVICE(LPC11C24/301, 0.000000, 0) HARDWA
RE(BOOTEXEC, 50, 100) ERASE(DEVICE, PROTECTISP) HEXFILE(hexfiles\fsm_can_1_02.he
x, NOCHECKSUMS, NOFILL, PROTECTISP) VERIFY(hexfiles\fsm_can_1_02.hex, NOCHECKSUM
S)
Flash Magic Version 11.20.5190
8051/XA Driver Version 3.55.5190
ARM UART Driver Version 5.06.5189
ARM Cortex UART Driver Version 8.41.5185
ARM Ethernet Driver Version 2.25.5190
ARM Cortex Ethernet Driver Version 2.70.5189
ARM CAN Driver Version 3.36.5044
(C) Embedded Systems Academy 2000-2018 All rights reserved
NON PRODUCTION USE ONLY
  
```

Screen display for incorrectly plugged-in ribbon cable or missing 24 V supply



```

F:\flasher>REM FSM CAN Programmer V1.0

F:\flasher>set arg1=13

F:\flasher>cd flasher

F:\flasher\flasher>fm.exe COM(13,57600) DEVICE(LPC11C24/301, 0.000000, 0) HARDWA
RE(BOOTEEXEC, 50, 100) ERASE(DEVICE, PROTECTISP) HEXFILE(hexfiles\fsm_can_1_02.he
x, NOCHECKSUMS, NOFILL, PROTECTISP) VERIFY(hexfiles\fsm_can_1_02.hex, NOCHECKSUM
S)
Flash Magic Version 11.20.5190
8051/XA Driver Version 3.55.5190
ARM UART Driver Version 5.06.5189
ARM Cortex UART Driver Version 8.41.5185
ARM Ethernet Driver Version 2.25.5190
ARM Cortex Ethernet Driver Version 2.70.5189
ARM CAN Driver Version 3.36.5044
(C) Embedded Systems Academy 2000-2018 All rights reserved
NON PRODUCTION USE ONLY
Connection failed: comms error (Unable to communicate. Failed to open COM13)

F:\flasher\flasher>cd..

F:\flasher>
  
```

Screen display for incorrectly selected COM interface

## NOTES

## NOTES

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